

FIG. 1A is a perspective view of a prosthetic arm 100 in a flexed position. The arm 100 includes a shoulder joint 101, an upper arm 102, a forearm 103, and a hand 104. The shoulder joint 101 is connected to a base 105. The upper arm 102 is connected to the shoulder joint 101 and the forearm 103. The forearm 103 is connected to the hand 104. The hand 104 includes a palm 106 and fingers 107. The arm 100 is shown in a flexed position, with the forearm 103 bent at the elbow joint 108. The arm 100 is shown in a perspective view, with the base 105 at the top and the hand 104 at the bottom. The arm 100 is shown in a flexed position, with the forearm 103 bent at the elbow joint 108. The arm 100 is shown in a perspective view, with the base 105 at the top and the hand 104 at the bottom.

100

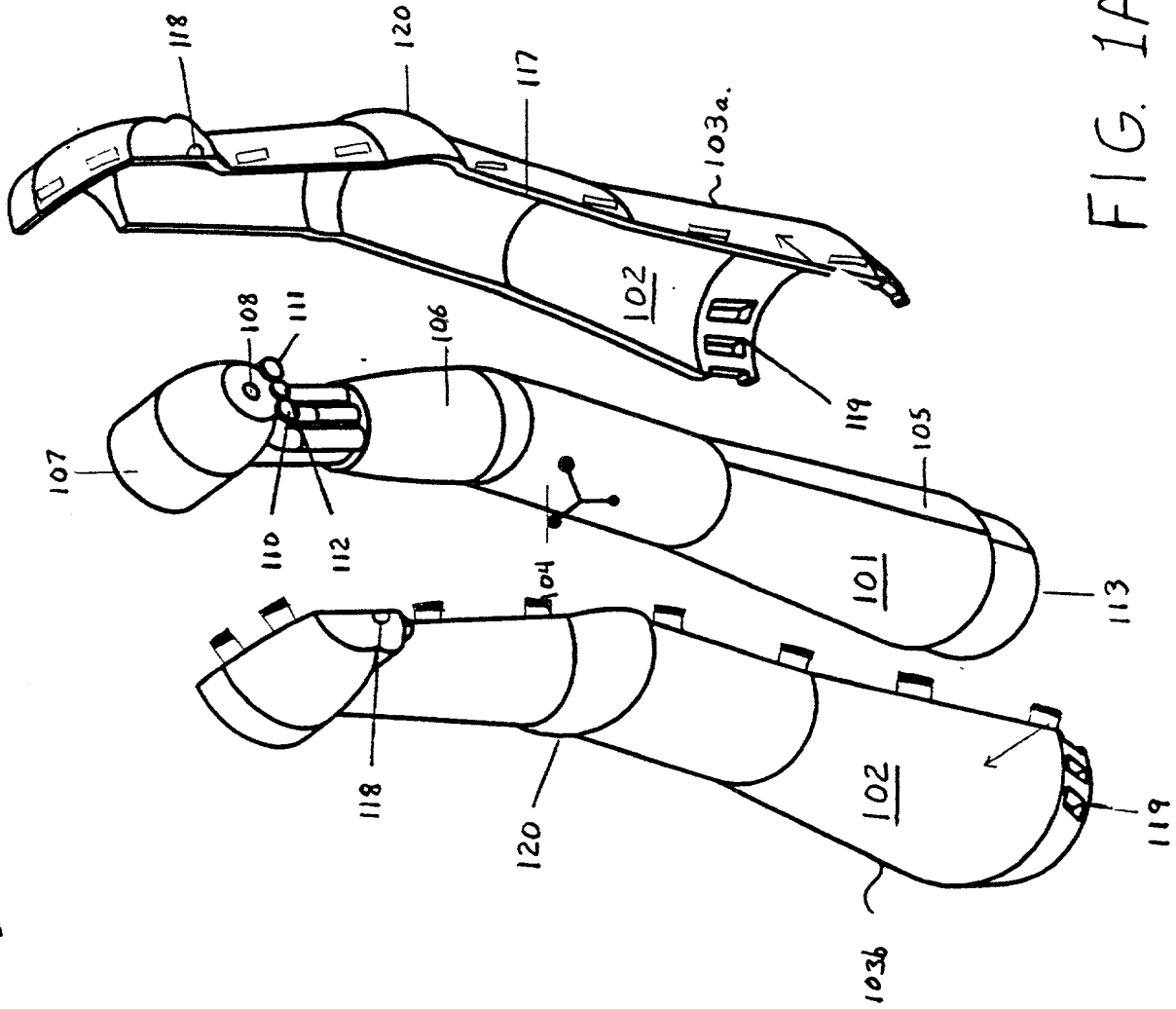


FIG. 1A

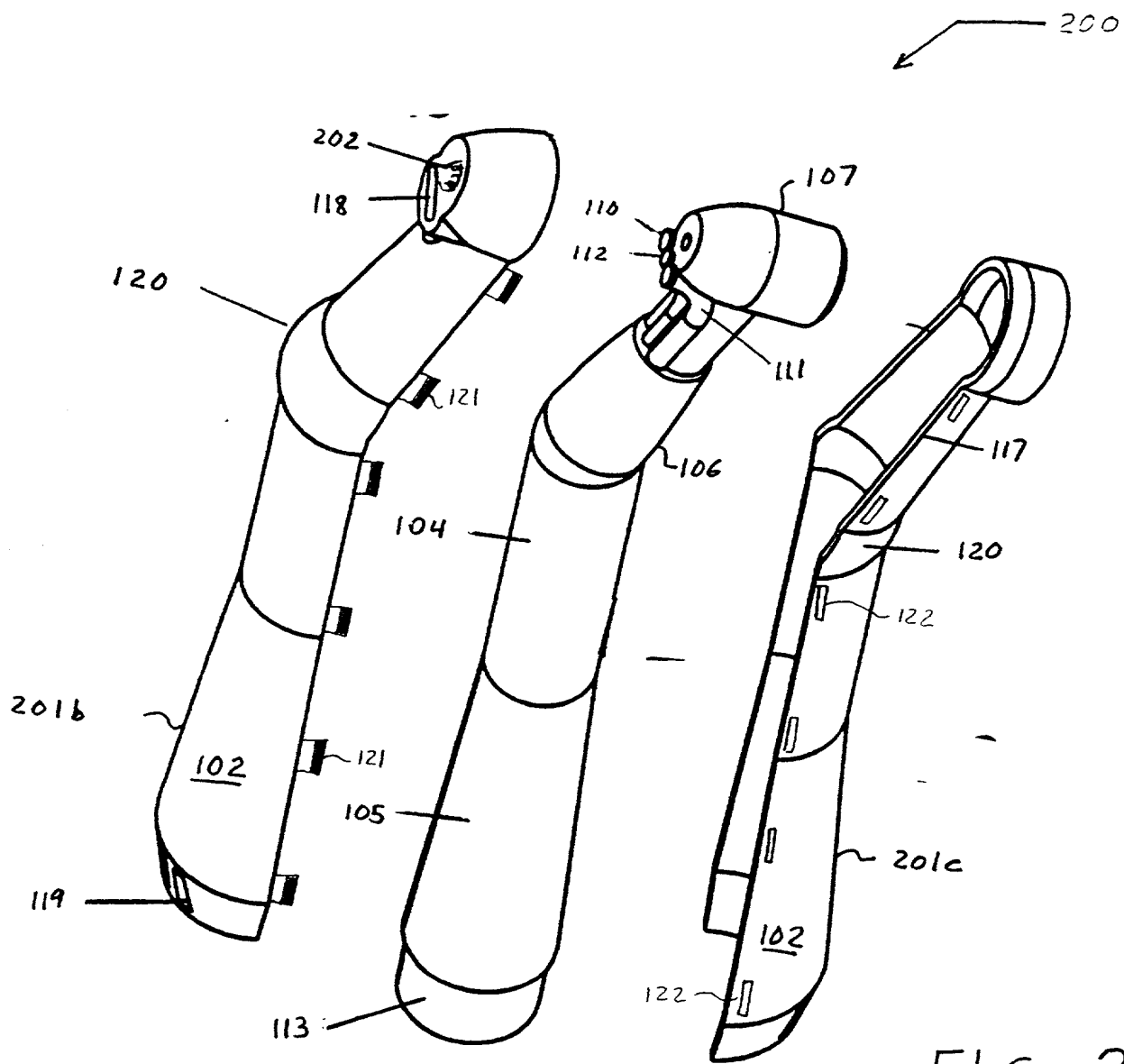


FIG. 2

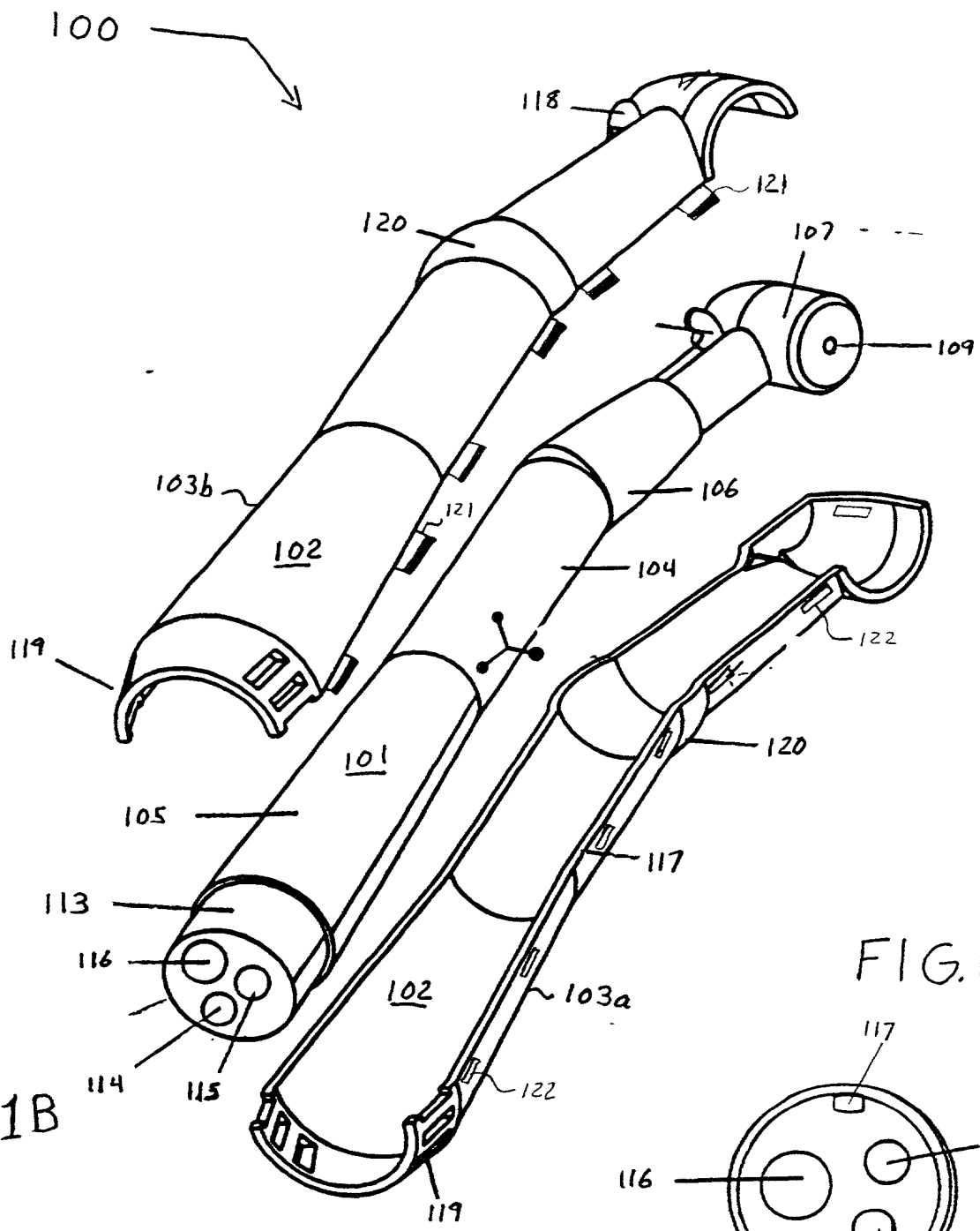


FIG. 1B

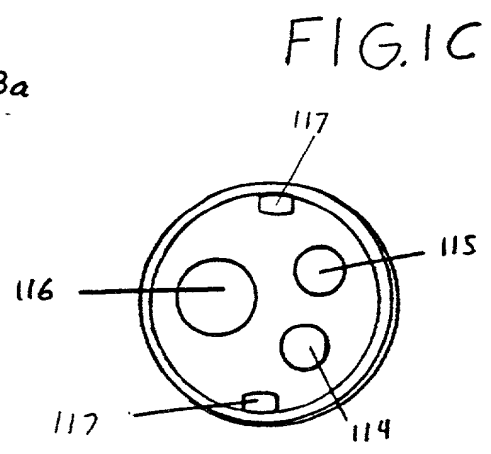


FIG. 1C

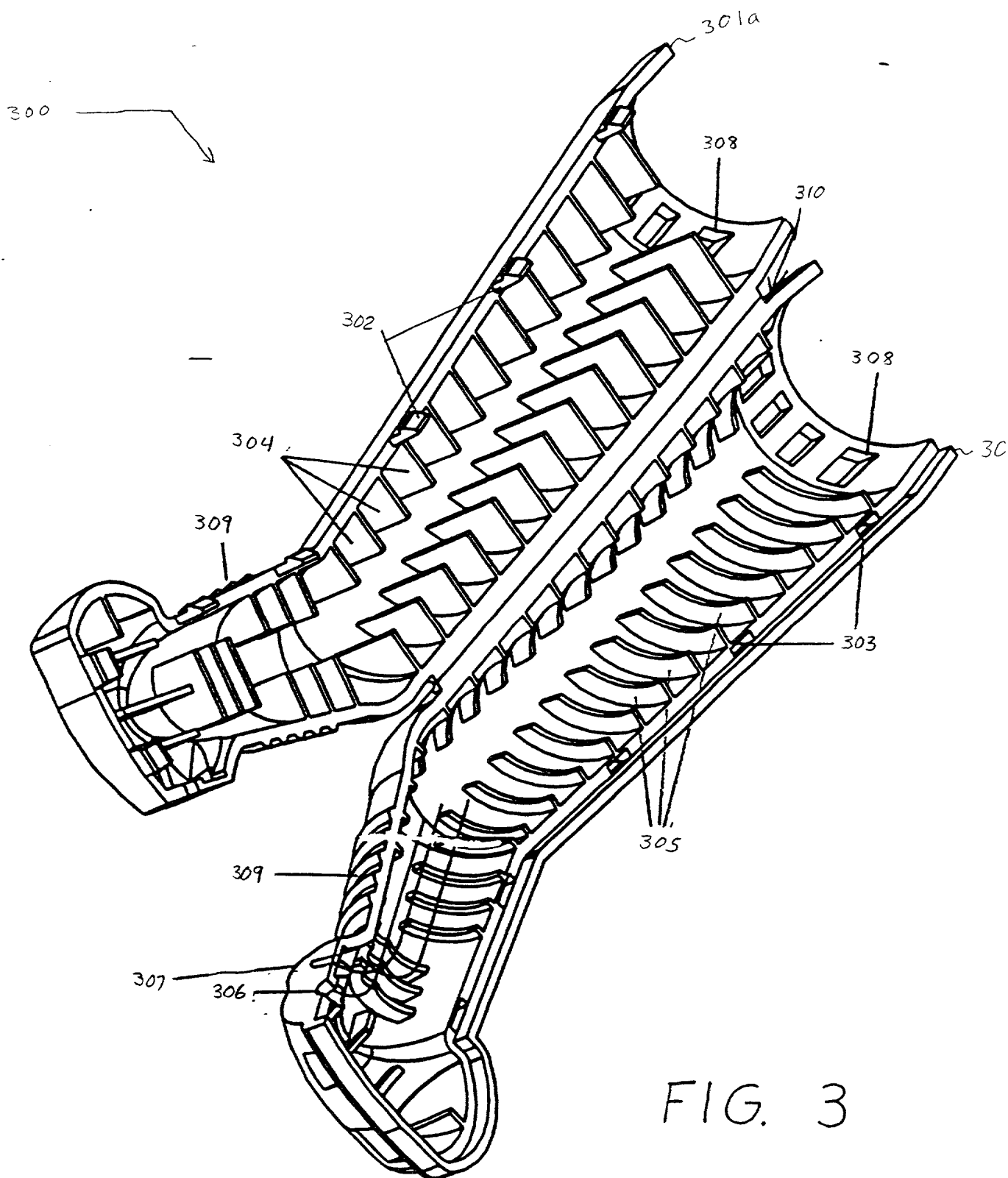
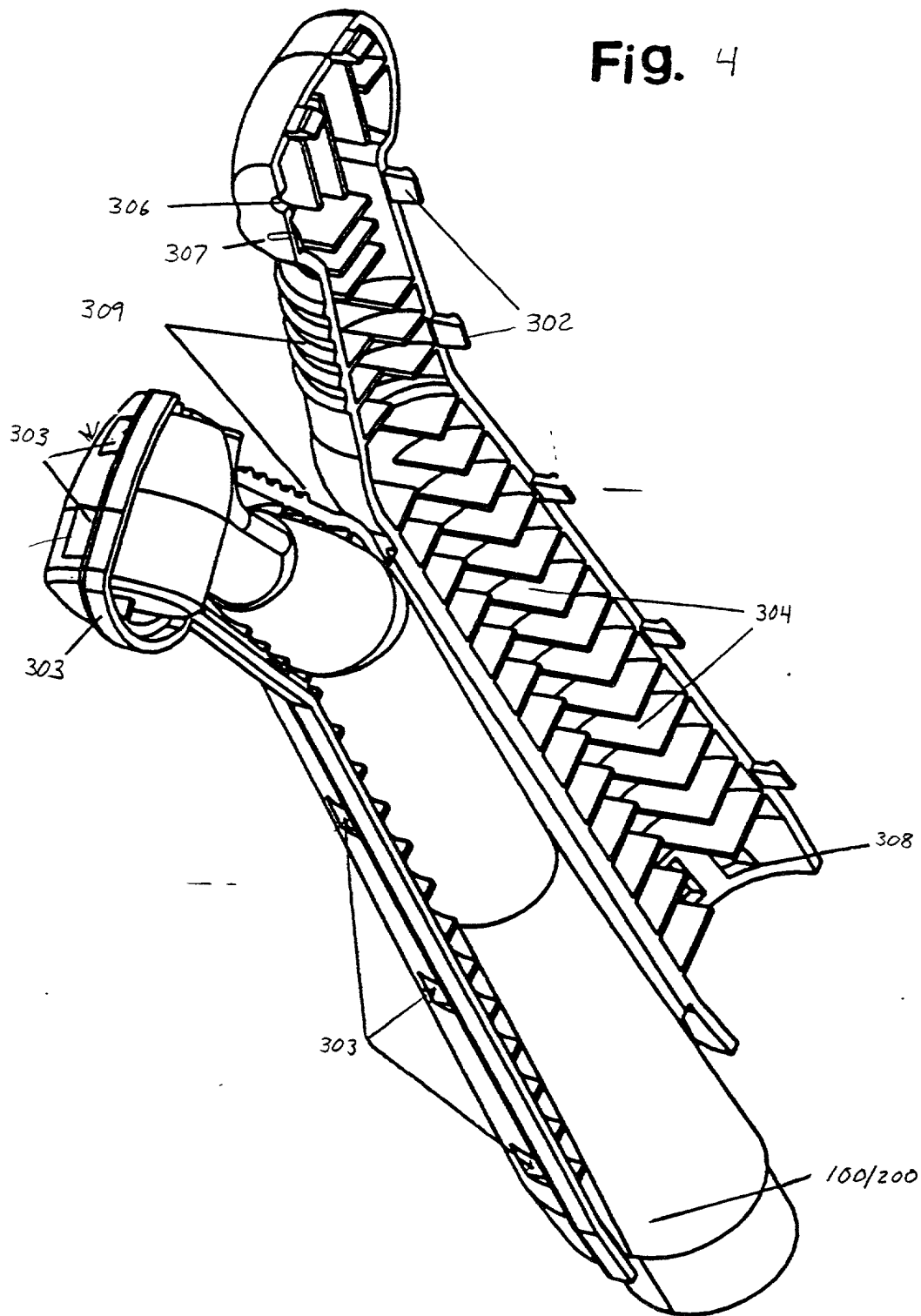


Fig. 4



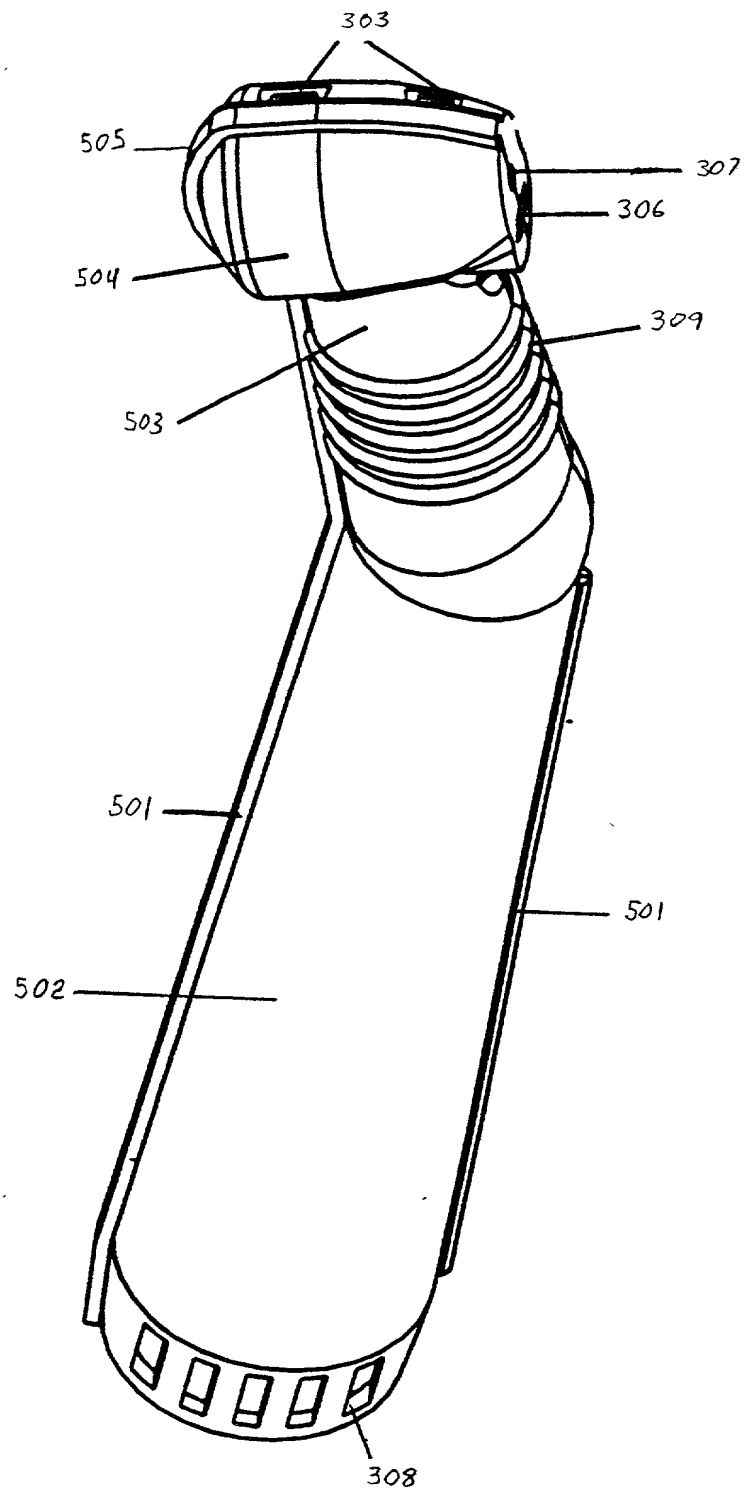


Fig 5

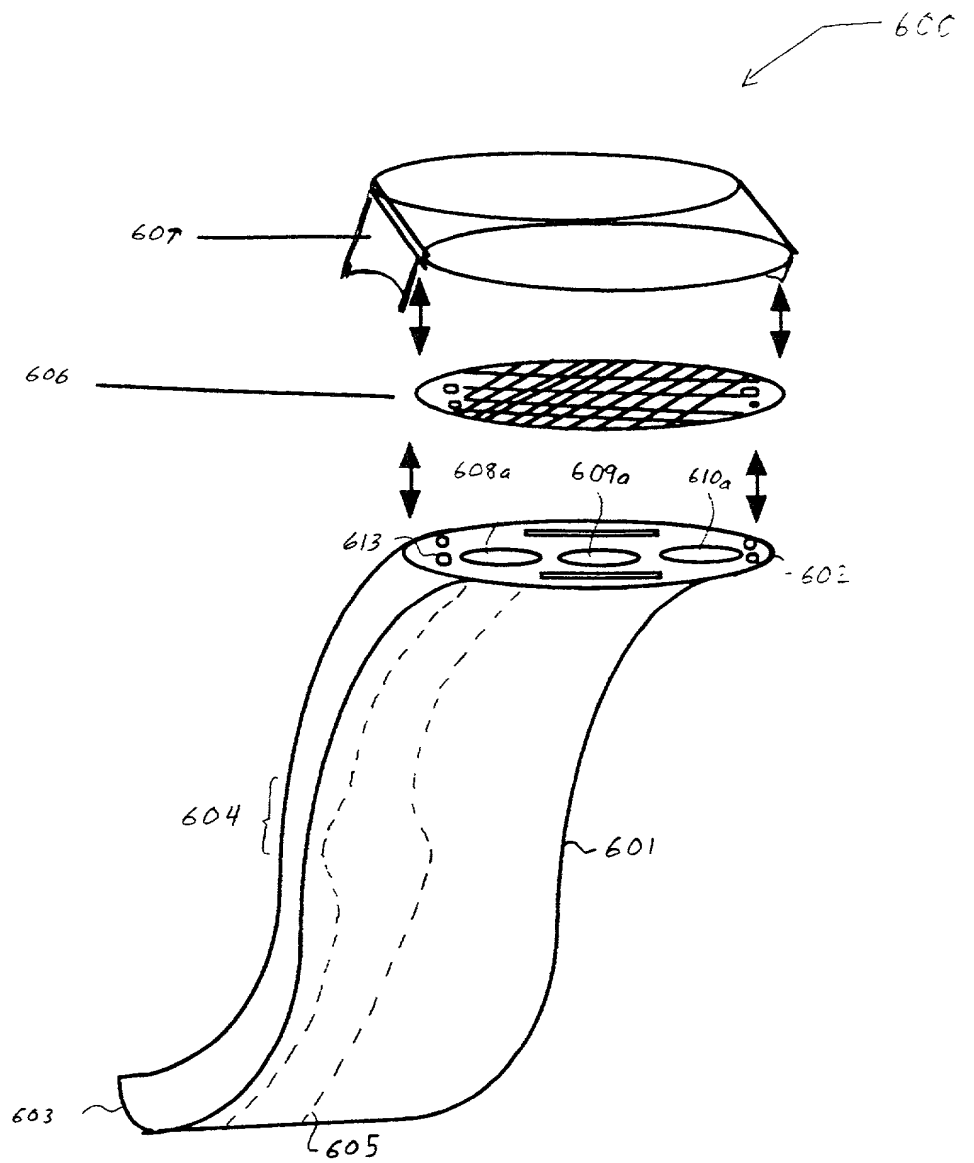


FIG. 6A

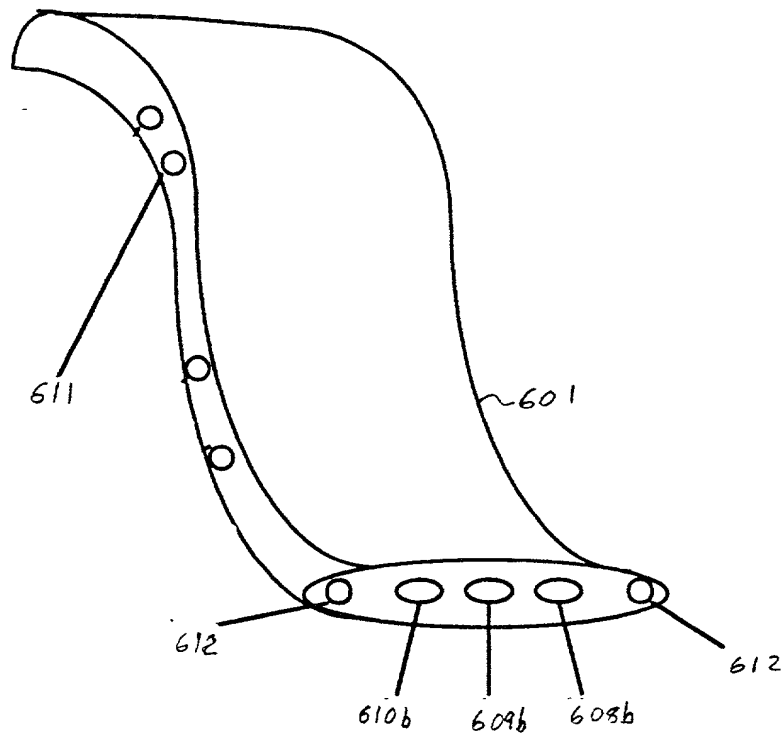
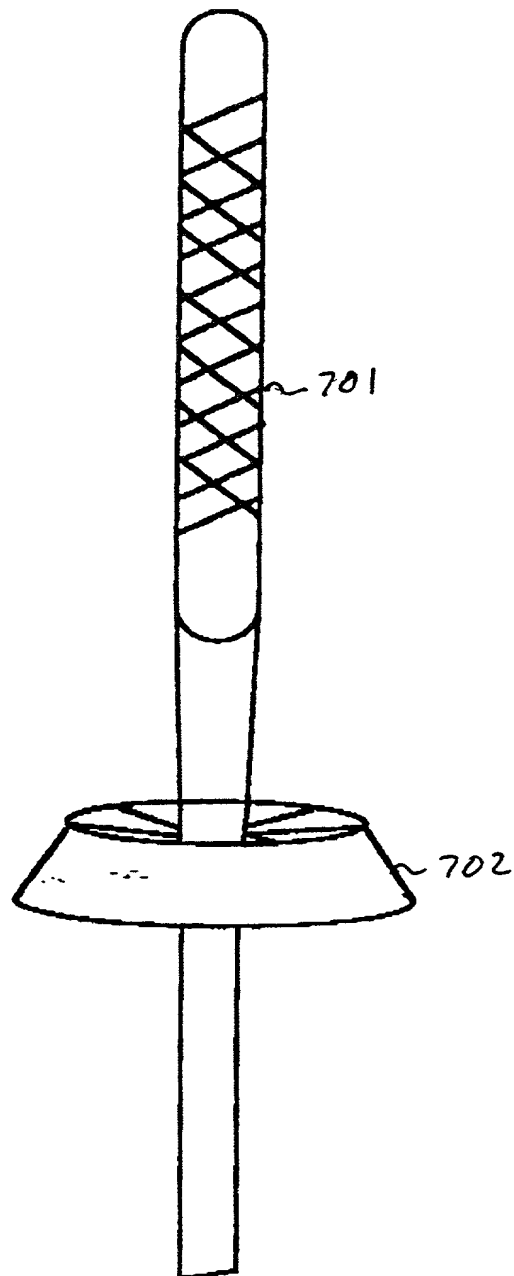


FIG. 6B



FIG. 7A



704

701



FIG. 7B

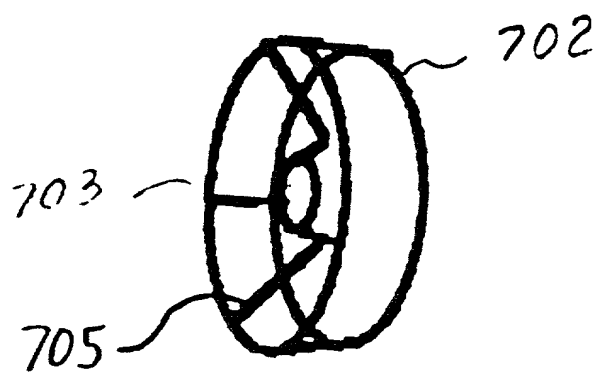


Fig. 7C

FIG. 8

